Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S2	54	(US-20020077223-\$ or US-20020193211-\$ or US-20030060340-\$ or US-20040005963-\$ or US-200400058754-\$ or US-20040058787-\$ or US-2004009851-\$ or US-20040097347-\$ or US-20040110605-\$ or US-20040110606-\$ or US-20040214694-\$ or US-20040214694-\$ or US-20040224826-\$ or US-20050181913-\$).did. or (US-0835796-\$ or US-3888481-\$ or US-3850533-\$ or US-3888481-\$ or US-4387892-\$ or US-4401303-\$ or US-4593900-\$ or US-4702472-\$ or US-4765609-\$ or US-4702472-\$ or US-4946159-\$ or US-4974833-\$ or US-4989862-\$ or US-5256069-\$ or US-5281191-\$ or US-5503606-\$ or US-5509875-\$ or US-5716302-\$ or US-5792032-\$ or US-5971398-\$ or US-6033349-\$ or US-6042522-\$). did. or (US-6063011-\$ or US-6110079-\$ or US-6139328-\$ or US-6152863-\$ or US-6139328-\$ or US-6416445-\$ or US-6435937-\$ or US-6416445-\$ or US-6435937-\$ or US-6416445-\$ or US-6808477-\$ or US-6872172-\$).did. or (US-0835796-\$ or US-3387842-\$). did. or (EP-173129-\$).did.	US-PGPUB; USPAT; USOCR; EPO	OR	ON	2005/11/02 09:58
S4	16	S2 and (electric or motor or (power adj supply))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/02 09:59

S16	63	(US-20020077223-\$ or US-20020193211-\$ or US-20030060340-\$ or US-20040005963-\$ or US-20040053754-\$ or US-20040053754-\$ or US-20040058787-\$ or US-200400110605-\$ or US-20040110606-\$ or US-20040214694-\$ or US-2004024826-\$ or US-2004024826-\$ or US-20050181913-\$).did. or (US-0835796-\$ or US-388481-\$ or US-3804406-\$ or US-3888481-\$ or US-4387892-\$ or US-4702472-\$ or US-4765609-\$ or US-4765609-\$ or US-4974833-\$ or US-4946159-\$ or US-5256069-\$ or US-5281191-\$ or US-5503606-\$ or US-5281191-\$ or US-5503606-\$ or US-5902217-\$ or US-5716302-\$ or US-5902217-\$ or US-590325-\$ or US-6033349-\$ or US-6042522-\$). did. or (US-6063011-\$ or US-6110079-\$ or US-6139328-\$ or US-6152863-\$ or US-6152960-\$ or US-6241640-\$ or US-6280351-\$ or US-6416445-\$ or US-6435937-\$ or US-6416445-\$ or US-6435937-\$ or US-669601-\$ or US-6808477-\$ or US-647747-\$ or US-6808477-\$ or US-6872172-\$ or US-6808477-\$ or US-647747-\$ or US-6808477-\$ or US-647747-\$ or US-6808477-\$ or US-647747-\$ or US-6435937-\$ or US-647747-\$ or US-6435937-\$ or US-647747-\$ or US-6808477-\$ or US-647747-\$ or US-6808477-\$ or US-647747-\$ or US-6808477-\$ or US-647747-\$ or US-64088315-\$ or US-5052683-\$ or US-4088315-\$ or US-4307891-\$ or US-D269882-\$). did. or (US-0835796-\$ or US-3387842-\$).did. or (US-0835796-\$ or US-3387842-\$).did. or (US-0835796-\$ or US-3387842-\$).did. or (US-0835796-\$ or US-3387842-\$). did.	US-PGPUB; USPAT; USOCR; EPO	OR	ON	2005/11/02 18:07
S17	2	S16 and motor and gear and shaft	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/02 18:14
S18	9	S16 and motor and shaft	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/02 18:32

S19	944945	motor and shaft	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/02 18:33
S20	13590	S19 and robot	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/02 18:33
S21	130	S20 and torso	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/02 18:34
S22	3776	S20 and arm and gear	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/02 18:33
S23	81	S21 and S22	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/02 18:34
S27	1149	318/568.11	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/03 13:38
S28	217	S27 and shaft and gear	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/03 14:12
S29	106	S28 and (shaft with gear)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/03 18:38

S30	60777	"29" and (arm with gear)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR .	ON	2005/11/03 18:38
S31	1149	318/568.11	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/03 18:38
S32	217	S31 and shaft and gear	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/03 18:38
S33	106	S32 and (shaft with gear)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/03 18:38
S34	49	S33 and (arm with gear)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 12:49
S36	1149	318/568.11	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 12:49
S37	217	S36 and shaft and gear	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 12:49
S38	106	S37 and (shaft with gear)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 12:49

S39	49	S38 and (arm with gear)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 12:49
S40	48	S39 and motor	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 18:18
S41	605845	motor with shaft	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 18:18
S42	222811	S41 and arm	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 18:18
S43	6015	S42 and robot	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 18:18
S45	1	S43 and ((rocker adj linkage) or (tie adj rod adj linkage))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 18:49

S48	91	(US-20020061706-\$ or	US-PGPUB;	OR	ON	2005/11/07 19:26
1		US-20020077223-\$ or	USPAT;			
		US-20020081937-\$ or	USOCR;	ļ		
1		US-20020193045-\$ or	EPO			
		US-20020193211-\$ or				
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		US-20040224826-\$ or				
		US-20050181913-\$).did. or				
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1		US-4989862-\$ or US-5018977-\$ or				
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		US-6658962-\$ or US-6669601-\$ or				
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		US-6871115-\$ or US-6872172-\$ or				
		US-6922610-\$ or US-6923613-\$ or				
		US-D269882-\$ or US-4879499-\$ or				
į		US-5132601-\$).did. or				
		(US-0835796-\$ or US-3387842-\$).				
		did. or (EP-173129-\$).did.				

S49	8	S48 and solenoid	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 19:37
S50	62260	motor with solenoid	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 19:37
S51	969	S50 and robot	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON .	2005/11/07 19:37
S52	688	S51 and arm	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 19:38
S53	303	S52 and (fight\$3 or box\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/11/07 19:38
S54	173	S52 and (fight\$3 or box\$3)	USPAT	OR	ON	2005/11/07 19:45
S55	1147	motor with solenoid with arm	USPAT	OR	ON	2005/11/07 19:45
S56	50	S55 and robot	USPAT	OR	ON	2005/11/07 19:51